

# AMS 241, Fall 2010, Homework 2

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## 1 Gibbs Sampling Equations

The model we are studying is:

$$\begin{aligned}y_i | \theta_i, \phi &\sim k_N(y_i; \theta_i, \phi), \quad i = 1, \dots, n \\ \theta_i | G &\sim G, \quad i = 1, \dots, n \\ G | \alpha, \mu, \tau^2 &\sim DP(\alpha, G_0 = N(\mu, \tau^2)) \\ \alpha &\sim \text{Gamma}(a_\alpha, b_\alpha) \\ \mu &\sim N(a_\mu, b_\mu) \\ \tau^2 &\sim \text{InvGamma}(a_{\tau^2}, b_{\tau^2}) \\ \phi &\sim \text{InvGamma}(a_\phi, b_\phi)\end{aligned}$$

### 1.1 Posterior $\theta_i$

$$p(\theta_i | y_i, \{\theta_k, k \neq i\}, \alpha, \phi, \mu, \tau^2, \text{data}) = \frac{q_0 h(\theta_i | \phi, \mu, \tau^2, y_i) + \sum_{j=1}^{n^*} n_j^- q_j \delta_{\theta_j^*}(\theta_i)}{q_0 + \sum_{j=1}^{n^*} n_j^- q_j} \quad (1)$$

where

$$\begin{aligned}q_j &= N(y_i; \theta_j^*, \phi) \\ q_0 &= \alpha \int_{-\infty}^{\infty} k(y_i; \theta_i, \phi) g_0(\theta_i | \mu, \tau^2) d\theta_i \\ &= \alpha \int_{-\infty}^{\infty} N(y_i; \theta_i, \phi) N(\theta_i | \mu, \tau^2) d\theta_i \\ &= \alpha N(y_i; \mu, \phi + \tau^2)\end{aligned}$$

and

$$\begin{aligned}
h(\theta_i|\phi, \mu, \tau^2, y_i) &= C \cdot k_N(y_i|\theta_i, \phi)g_0(\theta_i|\mu, \tau^2) \\
&= C \cdot N(y_i; \theta_i, \phi)N(\theta_i|\mu, \tau^2) \\
&= N(\theta_i; m, v)
\end{aligned}$$

where

$$m = \frac{\mu/\tau^2 + y_i/\phi}{1/\tau^2 + 1/\phi} \quad v = \frac{1}{1/\tau^2 + 1/\phi}$$

So  $\theta_i$  will either be a new distinct  $\theta$  value drawn from  $N(\theta_i; m, v)$  with probability proportional to  $q_0$ , or equal to an existing  $\theta_j$  value with probability proportional to  $n_j^- q_j$ .

## 1.2 Posterior $\theta_j^*$

$$\begin{aligned}
p(\theta_j^*|w, n^*, \mu, \tau^2, \phi, data) &= C \cdot \left[ \prod_{i:w_i=j} k(y_i|\theta_j^*, \phi) \right] g_0(\theta_j^*|\mu, \tau^2) \\
&= C \cdot \left[ \prod_{i:w_i=j} N(y_i|\theta_j^*, \phi) \right] N(\theta_j^*|\mu, \tau^2) \\
&= N(\theta_j^*; m^*, v^*)
\end{aligned} \tag{2}$$

where

$$m^* = \frac{\mu/\tau^2 + n_j \bar{y}_j/\phi}{1/\tau^2 + n_j/\phi} \quad v = \frac{1}{1/\tau^2 + n_j/\phi}$$

So for each individual cluster (component)  $j$ , we independently draw a value for  $\theta_j$  from the distribution defined in equation [2].

## 1.3 Posterior $\phi$

$$\begin{aligned}
p(\phi|\boldsymbol{\theta}, data) &= C \cdot p(\phi) \prod_{i=1}^n k(y_i|\theta_i, \phi) \\
&= C \cdot \text{InvGamma}(a_\phi, b_\phi) \prod_{i=1}^n N(y_i|\theta_i, \phi) \\
&= C \cdot \phi^{-(a_\phi+1)} \exp(-b_\phi/\phi) \prod_{i=1}^n \phi^{-1/2} \exp\left[\frac{-1}{2\phi}(y_i - \theta_i)^2\right] \\
&= C \cdot \phi^{-(a_\phi+n/2+1)} \exp(-b_\phi/\phi) \exp\left[\sum_{i=1}^n \frac{-1}{2\phi}(y_i - \theta_i)^2\right] \\
&= C \cdot \phi^{-(a_\phi+n/2+1)} \exp\left[\frac{-1}{\phi} \left(b_\phi + \frac{nv}{2}\right)\right] \\
&= \text{InvGamma}(a_\phi + n/2, b_\phi + nv/2)
\end{aligned} \tag{3}$$

where

$$nv = \sum_{i=1}^n (y_i - \theta_i)^2$$

## 1.4 Posterior $\mu, \tau^2$

$$\begin{aligned} p(\mu, \tau^2 | \boldsymbol{\theta}^*) &= C \cdot p(\mu) p(\tau^2) \prod_{i=1}^{n^*} g_0(\theta_i^* | \mu, \tau^2) \\ &= C \cdot N(\mu | a_\mu, b_\mu) \text{InvGamma}(\tau^2 | a_{\tau^2}, b_{\tau^2}) \prod_{i=1}^{n^*} N(\theta_i^* | \mu, \tau^2) \end{aligned}$$

We are not in a conjugate prior setting in this case for  $p(\mu, \tau^2 | \boldsymbol{\theta}^*)$ , but we can easily compute the conditional distributions needed for Gibbs sampling:

$$\begin{aligned} p(\mu | \tau^2, \boldsymbol{\theta}^*) &= C \cdot N(\mu | a_\mu, b_\mu) \prod_{i=1}^{n^*} N(\theta_i^* | \mu, \tau^2) \\ &= N(m_\mu, s_\mu^2) \end{aligned} \tag{4}$$

where

$$m_\mu = \frac{a_\mu/b_\mu + n^* \bar{\boldsymbol{\theta}}^*/\tau^2}{1/b_\mu + n^*/\tau^2} \quad s_\mu^2 = \frac{1}{1/b_\mu + n^*/\tau^2}$$

where  $n^*$  is the number of distinct  $\theta^*$  values and  $\bar{\boldsymbol{\theta}}^*$  is the mean of the distinct  $\theta^*$  values.

$$p(\tau^2 | \mu, \boldsymbol{\theta}^*) = C \cdot \text{InvGamma}(\tau^2 | a_{\tau^2}, b_{\tau^2}) \prod_{i=1}^{n^*} N(\theta_i^* | \mu, \tau^2)$$

Using the same algebraic manipulation as was done for the posterior of  $\phi$  above, we have:

$$p(\tau^2 | \mu, \boldsymbol{\theta}^*) = \text{InvGamma}(a_{\tau^2} + n^*/2, b_{\tau^2} + n^*\nu/2) \tag{5}$$

where

$$n^*\nu = \sum_{i=1}^{n^*} (\theta_i^* - \mu)^2$$

## 1.5 Posterior $\alpha$

Here we just re-iterate the sampling scheme for  $\alpha$  using the auxiliary variable scheme outlined by Escobar and West, 1995. First we draw  $\eta$  from :

$$p(\eta | \alpha, \text{data}) = \text{Beta}(\alpha + 1, n) \tag{6}$$

Define probability  $p = (a_\alpha + n^* - 1)/(n(b_\alpha - \log(\eta)) + a_\alpha + n^* - 1)$ , and draw:

$$\begin{aligned} \text{with probability } p &: \quad \alpha | \eta, n^*, \text{data} \sim \text{Gamma}(a_\alpha + n^*, b_\alpha - \log(\eta)) \\ \text{with probability } 1 - p &: \quad \alpha | \eta, n^*, \text{data} \sim \text{Gamma}(a_\alpha + n^* - 1, b_\alpha - \log(\eta)) \end{aligned} \tag{7}$$

## 1.6 Overview of Gibbs Sampling Scheme

A brief overview of the Gibbs sampling scheme is shown below. In our sampler, we maintain a *state* structure which consists of the  $\theta_i$  values, the cluster (component) membership index for each  $y_i$ , and the values of all the parameters  $\alpha, \mu, \tau^2, \phi$ .

### 1.6.1 Initialization

At initialization, we assign each of the  $N$   $y_i$  observations to belong to a different cluster, thus starting out with  $N$  separate clusters (components). Each cluster is initialized with a  $\theta_j^*$  drawn from  $g_0 = N(\mu, \tau^2)$  distribution, given the starting values of  $\mu, \tau^2$ .

### 1.6.2 MCMC Simulation

We typically run for 1000 burn-in iterations, followed by 4000 monitoring iterations. We arrived at the 1000/4000 values after preliminary experiments that showed that increasing iterations (e.g. 2000/10000) did not appreciably change the results, indicating that the chain had reached convergence.

The sampling scheme consists of :

- For  $i = 1..n$ , sample  $\theta_i$  from the mixed distribution defined by (1). Adjust cluster (component) membership indices of the data if an existing component was dropped or if a new component was added.
- For  $j = 1..n^*$ , sample  $\theta_j^*$  from (2).
- Sample  $\phi$  from (3).
- Sample  $\mu|\tau^2$  from (4) and  $\tau^2|\mu$  from (5).
- Sample  $\alpha$  using (6) and (7).

## 1.7 Predictive Distribution Calculations

The posterior predictive distribution for a new observation  $\theta_0$  is given by the Polya-Urn scheme:

$$p(\theta_0|n^*, \mathbf{w}, \boldsymbol{\theta}^*, \alpha, \phi) = \frac{\alpha}{\alpha + n} G_0(\theta_0|\phi) + \frac{1}{\alpha + n} \sum_{j=1}^{n^*} n_j \delta_{\theta_j^*}(\theta_0) \quad (8)$$

The posterior predictive distribution for a new  $y_0$  is given by :

$$p(y_0|data) = \int \int k(y_0; \theta_0, \phi) p(\theta_0|n^*, \mathbf{w}, \boldsymbol{\theta}^*, \alpha, \phi) p(n^*, \mathbf{w}, \boldsymbol{\theta}^*, \alpha, \phi|data) \quad (9)$$

Thus given  $B$  sets of samples from our MCMC output, we can obtain samples from  $p(y_0|data)$  as follows: for each set  $b$  of posterior parameter values in the MCMC output, first draw  $\theta_{0,b}$  from  $p(\theta_0|n^*, \mathbf{w}, \boldsymbol{\theta}^*, \alpha, \phi)$ , and then draw  $y_{0,b}$  from  $p(y_0|\theta_{0,b}, \phi_b) = N(\cdot; \theta_{0,b}, \phi_b)$

Samples from the prior predictive distribution  $p(y_0)$  are obtained as follows:

- Draw  $(\mu, \tau^2)$  from  $p(\mu)p(\tau^2)$ . Since  $p(\mu)$  and  $p(\tau^2)$  are independent of each other,  $p(\mu, \tau^2)$  does not form a conjugate prior for  $G_0 = N(\mu, \tau^2)$ . So we independently sample  $b$  times:
- $\tau_b^2 \sim InvGamma(a_{\tau^2}, b_{\tau^2})$
- $\mu_b \sim N(a_\mu, b_\mu)$
- $\theta_{0,b} \sim G_0 = N(\mu, \tau^2)$
- $y_{0,b} \sim \int N(y_{0,b}; \theta_{0,b}|\phi)p(\phi)d\phi = t_\nu(\theta_{0,b}, s^2)$ , a t distribution with  $\nu = 2a_\phi$  degrees of freedom, mean  $\theta_{0,b}$  and scale  $s^2 = b_\phi/a_\phi$

The derivation of  $y_{0,b} \sim t_\nu(\theta_{0,b}, s^2)$  is shown below:

$$\begin{aligned} \int N(y; \theta|\phi)IG(\phi; a, b)d\phi &= \int \frac{1}{\sqrt{2\pi\phi}} \exp\left[\frac{-1}{2\phi}(y - \theta)^2\right] \frac{b^a}{\Gamma(a)} \phi^{-(a+1)} \exp\left[\frac{-b}{\phi}\right] d\phi \\ &= C \cdot \int \phi^{-(a+1+1/2)} \exp\left[\frac{-1}{2\phi}((y - \theta)^2 + 2b)\right] d\phi \end{aligned}$$

Letting  $z = \frac{A}{2\phi}$

$$\phi = \frac{A}{2z}$$

$$|d\phi| = \frac{A}{2z^2} dz$$

where  $A = ((y - \theta)^2 + 2b)$  we get

$$\begin{aligned} &= C \cdot \int \left(\frac{A}{2z}\right)^{-(a+1+1/2)} \exp[-z] \frac{A}{2z^2} dz \\ &= C \cdot \left(\frac{A}{2}\right)^{-(a+1/2)} \int z^{(a+1/2-1)} \exp(-z) dz \\ &= C \cdot \left(\frac{A}{2}\right)^{-(a+1/2)} \Gamma(a + 1/2) \\ &= C \cdot \Gamma(a + 1/2) \left[\frac{1}{2}(y - \theta)^2 + b\right]^{-(a+1/2)} \\ &= C \cdot \Gamma(a + 1/2) b^{-(a+1/2)} \left[1 + \frac{(y - \theta)^2}{2b}\right]^{-(a+1/2)} \end{aligned}$$

which we recognize as the kernel of a t-distribution. Letting  $a = a_\phi = \nu/2$  and  $b = b_\phi = \nu s^2/2$  and filling in the constants, we get the familiar form of the t-distribution, namely:

$$y_{0,b} \sim \frac{\Gamma(\frac{\nu+1}{2})}{\Gamma(\frac{\nu}{2})} \frac{1}{\sqrt{\pi\nu s}} \left[1 + \frac{(y - \theta)^2}{\nu s^2}\right]^{-\frac{\nu+1}{2}}$$